

The Combinatorics of Finite Element Methods

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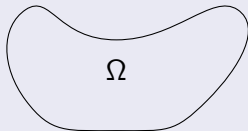
- ① From finite elements to the Euler characteristic.
 - Finite element spaces let us numerically solve PDEs.
 - Using naïve finite element spaces can give us wrong answers.
 - Finite element spaces that do work well are related to the Euler characteristic $V - E + F$.
- ② From the Euler characteristic to cohomology (1500s–1930s).
 - An introduction to Euler characteristic and cohomology.
 - Both numerical analysis and cohomology are ways of going between the continuous world and the discrete world.
 - Some finite element spaces developed by numerical analysts in the 1970s and 1980s were actually rediscoveries of spaces developed by geometers decades earlier.
- ③ From cohomology to finite elements (Arnold, Falk, Winther, 2006–2010).
 - Finite element spaces that respect cohomology work well.
 - Finite element spaces that do not respect cohomology might give wrong answers.

Sample Problem

- Given $f: \Omega \rightarrow \mathbb{R}$, find $u: \Omega \rightarrow \mathbb{R}$ such that

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f$$

and u vanishes on the boundary.

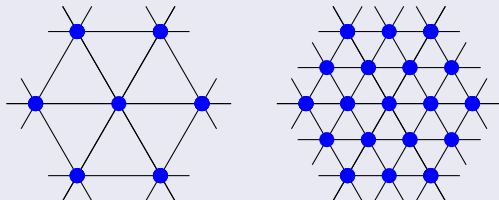


Discretization

- To solve numerically, we must discretize.
- We need a finite-dimensional space of functions that “approximates” the full infinite-dimensional space of possible u .

Finite-dimensional function spaces

Continuous piecewise linear functions to \mathbb{R}



Continuous piecewise polynomial functions to \mathbb{R}

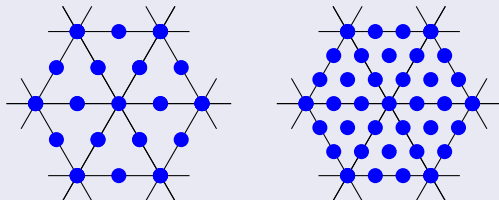
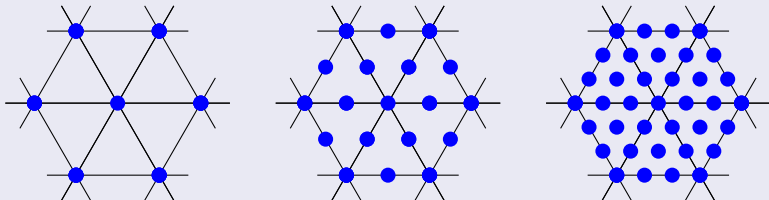


Figure: Piecewise quadratic (left) and piecewise cubic (right)

Degrees of freedom

Piecewise linear/quadratic/cubic continuous scalar-valued functions



Degrees of freedom (DOFs)

- One value per degree of freedom (blue dot)
 - yields a unique function on each triangle, and
 - enforces continuity between adjacent triangles.

Piecewise linear	\mathbb{R}^V
Piecewise quadratic	\mathbb{R}^{V+E}
Piecewise cubic	\mathbb{R}^{V+2E+F}

What about vector fields?

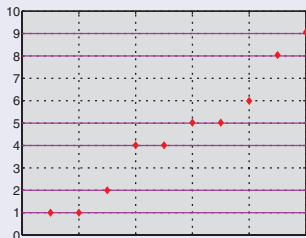
A naïve approach

Use continuous piecewise polynomial vector fields.

Eigenvalues of the curl curl operator

On a square domain, find a vector field u (with appropriate boundary conditions) such that $\text{curl curl } u = \lambda u$.

Bad things happen with the naïve approach (AFW, 2010)



- Using vector fields with full continuity yields **false** eigenvalue $\lambda = 6$.
- To get the right eigenvalues, we need better finite element spaces of vector fields.

Gradients of piecewise smooth scalar fields

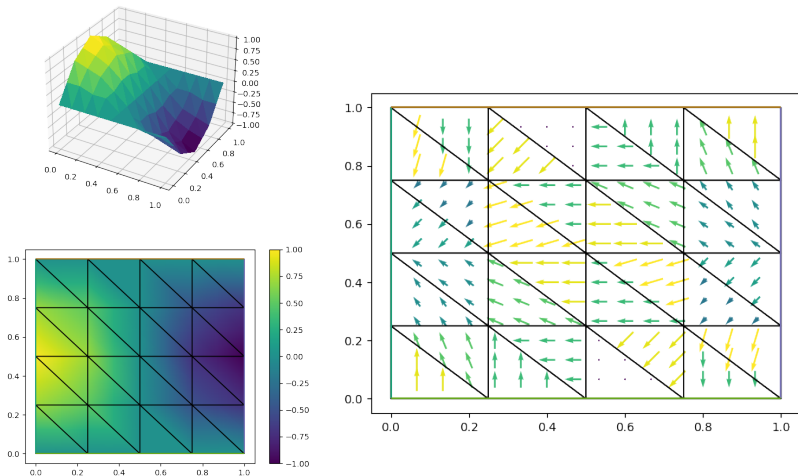


Figure: A piecewise linear function (left) and its gradient (right)

Continuity conditions

- We want only tangential continuity, not full continuity.

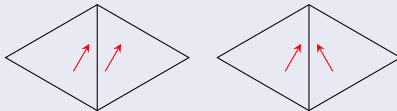


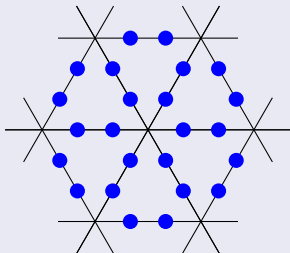
Figure: Full continuity (left) vs. tangential continuity (right)

- Why do these spaces work better?
 - Gradients of continuous piecewise smooth scalar fields only have tangential continuity.
 - Gradients of “valid objects” should be “valid objects”.
 - Having well-defined line integrals requires only tangential continuity.

Degrees of freedom (DOFs)

DOFs of piecewise linear vector fields with tangential continuity?

- Values should
 - uniquely specify a linear vector field on each triangle, and
 - enforce **tangential** continuity between adjacent triangles.



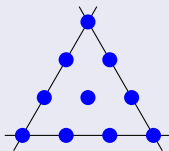
Higher degree?

Periodic Table of the Finite Elements

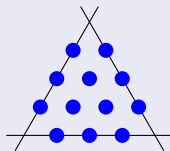
Complexes

A discrete complex

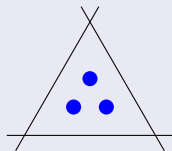
continuous piecewise cubic scalar fields $\xrightarrow{\text{grad}}$ tangentially continuous piecewise quadratic vector fields $\xrightarrow{\text{curl}}$ discontinuous piecewise linear scalar fields



$$\mathbb{R}^{V+2E+F}$$



$$\mathbb{R}^{3E+3F}$$



$$\mathbb{R}^{3F}$$

Euler characteristic

- This complex has the right Euler characteristic:

$$(V + 2E + F) - (3E + 3F) + 3F = V - E + F.$$

Euler characteristic

$$V - E + F = 2 \text{ (Maurolico, 1537)}$$




Name	Image	Vertices V	Edges E	Faces F	Euler characteristic: $\chi = V - E + F$
Tetrahedron		4	6	4	2
Hexahedron or cube		8	12	6	2
Octahedron		6	12	8	2
Dodecahedron		20	30	12	2
Icosahedron		12	30	20	2

Figure: Wikipedia, "Euler characteristic"

Works for all convex polyhedra

Soccer ball:

$$V - E + F = 60 - 90 + 32 = 2.$$

Euler characteristic for other shapes








Name	Image	χ
Interval		1
Circle		0
Disk		1
Sphere		2
Torus (Product of two circles)		0
Double torus		-2
Triple torus		-4

Figure: Wikipedia, “Euler characteristic”

From Euler characteristic to cohomology (1930s)

The continuous setting

Vector calculus in the plane (or on a surface)

scalar fields $\xrightarrow{\text{grad}}$ vector fields $\xrightarrow{\text{curl}}$ scalar fields

- If $E = \text{grad } \phi$, then $\text{curl } E = 0$. **always true**
- If $\text{curl } E = 0$, then $E = \text{grad } \phi$ for some ϕ . **not always true**

$$\text{curl } E = 0 \text{ but } E \neq \text{grad } \phi$$

The electric field around a solenoid

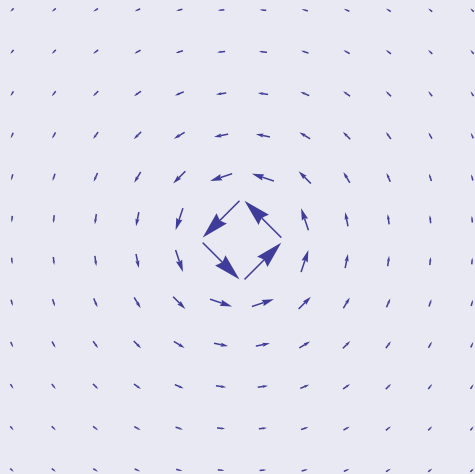


Figure: Wikipedia, "Irrotational vector field"

The de Rham complex

$$\text{scalar fields} \xrightarrow{\text{grad}} \text{vector fields} \xrightarrow{\text{curl}} \text{scalar fields}$$

The first cohomology group H^1

- Informally, the first cohomology group of a domain Ω is the set of counterexamples:
 - Vector fields E on Ω
 - whose curls are zero, but
 - which aren't gradients of a scalar field.
- Caveat: If E is a counterexample, then so is $E' := E + \text{grad } \psi$.
 - $\text{curl } E' = \text{curl } E + 0 = 0$.
 - If E is not a gradient then neither is E' .
- In the first cohomology group H^1 , we view E and E' as “equivalent counterexamples”.
- $\dim H^1$ counts the number of “holes” in the domain.

de Rham cohomology

The de Rham complex

scalar fields $\xrightarrow{\text{grad}}$ vector fields $\xrightarrow{\text{curl}}$ scalar fields

de Rham cohomology, informally

- H^0 : scalar fields ϕ whose gradients are zero.
- H^1 : vector fields E whose curls are zero but which aren't gradients.
- H^2 : scalar fields ρ which aren't curls.

The zeroth cohomology group H^0

- If $\text{grad } \phi = 0$ then ϕ is constant **only for connected domains**.
- So $\dim H^0 = 1$ **for connected domains**.
- $\dim H^0$ counts the number of connected components of the domain.

de Rham cohomology

The de Rham complex

scalar fields $\xrightarrow{\text{grad}}$ vector fields $\xrightarrow{\text{curl}}$ scalar fields

de Rham cohomology, informally

- H^0 : scalar fields ϕ whose gradients are zero.
- H^1 : vector fields E whose curls are zero but which aren't gradients.
- H^2 : scalar fields ρ which aren't curls.

The second cohomology group H^2

- For planar domains $H^2 = 0$ (every scalar field is a curl).
- For a closed surface S (e.g. sphere), H^2 is the constants.
 - If B is tangent to S then $\int_S \text{curl } B = 0$ by Stokes's theorem.
 - But $\int_S 1 \neq 0$, so 1 is not a curl.








From Euler characteristic to cohomology (1930s)

The continuous setting

Cohomology tells you the Euler characteristic

The Euler characteristic is

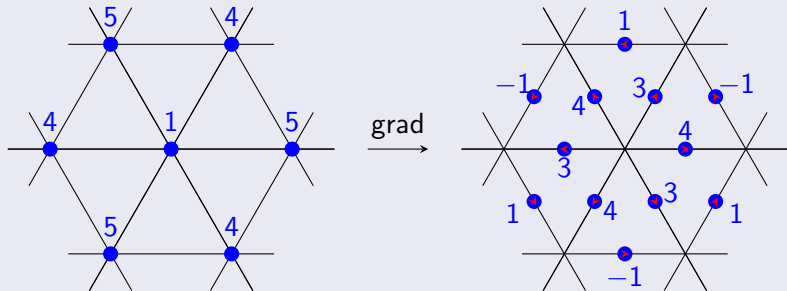
$$V - E + F,$$
$$\dim H^0 - \dim H^1 + \dim H^2.$$

Name	Image	χ
Interval		1
Circle		0
Disk		1
Sphere		2
Torus (Product of two circles)		0
Double torus		-2
Triple torus		-4

From Euler characteristic to cohomology (1930s)

The discrete setting

Discrete gradient



Fundamental theorem of line integrals

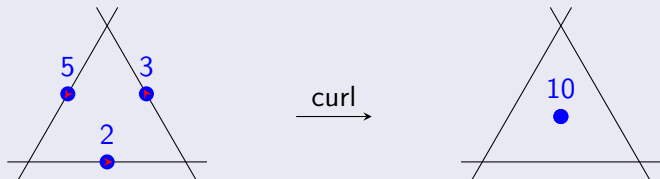
$$\int_C \text{grad } \phi = \phi \Big|_{v_0}^{v_1}$$

for a curve C from point v_0 to point v_1 .

From Euler characteristic to cohomology (1930s)

The discrete setting

Discrete curl



Green's/Stokes's Theorem

$$\int_S \text{curl } E = \int_C E$$

where C is the boundary of the surface S .

From Euler characteristic to cohomology (1930s)

The continuous complex (de Rham complex)

$$\text{scalar fields} \xrightarrow{\text{grad}} \text{vector fields} \xrightarrow{\text{curl}} \text{scalar fields}$$

The discrete complex (simplicial cochain complex)

$$\begin{array}{ccccc} \text{discrete} & \xrightarrow{\text{grad}} & \text{discrete} & \xrightarrow{\text{curl}} & \text{discrete} \\ \text{scalar fields} & & \text{vector fields} & & \text{scalar fields} \\ \mathbb{R}^V & \longrightarrow & \mathbb{R}^E & \longrightarrow & \mathbb{R}^F \end{array}$$

Theorem (De Rham's Theorem, 1931)

de Rham cohomology equals simplicial cohomology

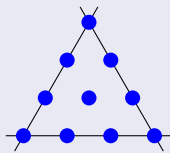
Corollary (Euler characteristic)

$$V - E + F = \dim H^0 - \dim H^1 + \dim H^2$$

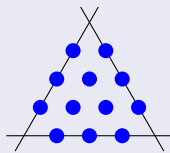
Back to finite elements

We've already seen a different discrete complex

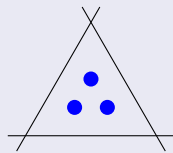
continuous piecewise cubic scalar fields $\xrightarrow{\text{grad}}$ tangentially continuous piecewise quadratic vector fields $\xrightarrow{\text{curl}}$ discontinuous piecewise linear scalar fields



$$\mathbb{R}^{V+2E+F}$$



$$\mathbb{R}^{3E+3F}$$



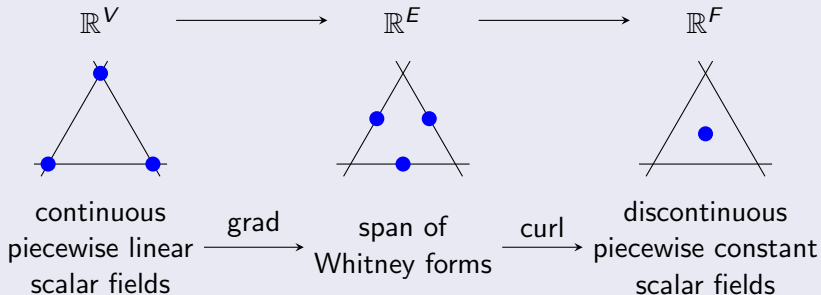
$$\mathbb{R}^{3F}$$

Euler characteristic and cohomology

- We saw this complex has the right Euler characteristic:
$$(V + 2E + F) - (3E + 3F) + 3F = V - E + F.$$
- Moreover, the cohomology is right, too.
 - That's why the spaces work well (Arnold, Falk, Winther, 2006).

Can we interpret simplicial cochains as finite elements?

Yes (Whitney, 1957)



Barycentric coordinates
(the standard simplex)

$$\left\{ (\lambda_1, \lambda_2, \lambda_3) \in \mathbb{R}_{\geq 0}^3 \mid \lambda_1 + \lambda_2 + \lambda_3 = 1 \right\}$$

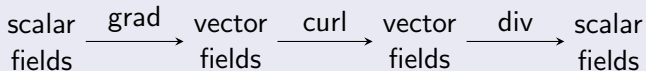
Whitney one-forms:

$$\begin{aligned} \lambda_1 d\lambda_2 - \lambda_2 d\lambda_1, \\ \lambda_2 d\lambda_3 - \lambda_3 d\lambda_2, \\ \lambda_3 d\lambda_1 - \lambda_1 d\lambda_3. \end{aligned}$$

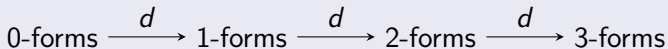
A modern language for vector calculus

The complex

- Vector calculus:



- Cartan, 1899:



Fundamental theorem

- Vector calculus:

- fundamental theorem of calculus/line integrals,
- Green's/Stokes's theorem,
- the divergence theorem.

- Cartan, 1945:

$$\int_{\Omega} d\omega = \int_{\partial\Omega} \omega.$$

Finite element exterior calculus (AFW, 2006)

The $\mathcal{P}_r\Lambda^k$ spaces

Definition (the $\mathcal{P}_r\Lambda^k$ spaces)

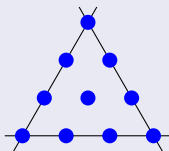
- Let \mathcal{T} be a triangulation of a manifold of dimension n .
- Let $\mathcal{P}_r\Lambda^k(\mathcal{T})$ be the space of k -forms that
 - are piecewise polynomial of degree at most r , and
 - are tangentially continuous.

Example

$\mathcal{P}_r\Lambda^0(\mathcal{T})$	continuous piecewise polynomial scalar fields
$\mathcal{P}_r\Lambda^1(\mathcal{T})$	tangentially continuous piecewise polynomial vector fields
$\mathcal{P}_r\Lambda^{n-1}(\mathcal{T})$	normally continuous piecewise polynomial vector fields
$\mathcal{P}_r\Lambda^n(\mathcal{T})$	discontinuous piecewise polynomial scalar fields

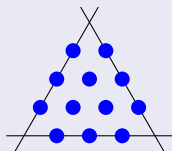
We've seen

continuous piecewise cubic scalar fields $\xrightarrow{\text{grad}}$ tangentially continuous piecewise quadratic vector fields $\xrightarrow{\text{curl}}$ discontinuous piecewise linear scalar fields



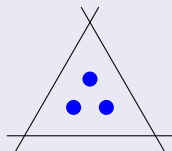
$\mathcal{P}_3\Lambda^0(T)$

d



$\mathcal{P}_2\Lambda^1(T)$

d



$\mathcal{P}_1\Lambda^2(T)$

Finite element exterior calculus

The $\mathcal{P}_r^- \Lambda^k$ spaces

On a single simplex T

- The Whitney k -forms have one DOF per k -dimensional face.
- Call their span $\mathcal{P}_1^- \Lambda^k(T)$.
 - Note: $\mathcal{P}_0 \Lambda^k(T) \subseteq \mathcal{P}_1^- \Lambda^k(T) \subseteq \mathcal{P}_1 \Lambda^k(T)$.
- Multiply Whitney forms by arbitrary scalar-valued polynomials of degree at most $r - 1$. Call the span of these $\mathcal{P}_r^- \Lambda^k(T)$.
 - So, $\mathcal{P}_{r-1} \Lambda^k(T) \subseteq \mathcal{P}_r^- \Lambda^k(T) \subseteq \mathcal{P}_r \Lambda^k(T)$.

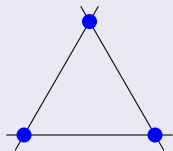
Definition (the $\mathcal{P}_r^- \Lambda^k$ spaces on a triangulation)

- Let \mathcal{T} be a triangulation of a manifold of dimension n .
- Let $\mathcal{P}_r^- \Lambda^k(\mathcal{T})$ be the space of k -forms that
 - are in $\mathcal{P}_r^- \Lambda^k(T)$ for each element T of the triangulation, and
 - are tangentially continuous.

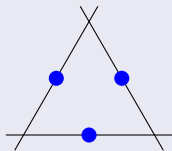
Duality between \mathcal{P} and \mathcal{P}^-

We've also seen

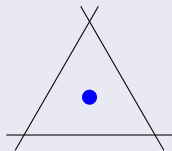
continuous piecewise linear scalar fields $\xrightarrow{\text{grad}}$ Whitney forms $\xrightarrow{\text{curl}}$ discontinuous piecewise constant scalar fields



$\mathcal{P}_1^- \Lambda^0(\mathcal{T})$



$\mathcal{P}_1^- \Lambda^1(\mathcal{T})$



$\mathcal{P}_1^- \Lambda^2(\mathcal{T})$

More complexes

Theorem (Arnold, Falk, Winther, 2006)

For a triangulation \mathcal{T} , the cohomology of the complexes

$$\mathcal{P}_r \Lambda^0(\mathcal{T}) \xrightarrow{d} \mathcal{P}_{r-1} \Lambda^1(\mathcal{T}) \xrightarrow{d} \dots \xrightarrow{d} \mathcal{P}_{r-n} \Lambda^n(\mathcal{T})$$

$$\mathcal{P}_r^- \Lambda^0(\mathcal{T}) \xrightarrow{d} \mathcal{P}_r^- \Lambda^1(\mathcal{T}) \xrightarrow{d} \dots \xrightarrow{d} \mathcal{P}_r^- \Lambda^n(\mathcal{T})$$

agrees with de Rham cohomology (provided $r \geq n$ in the first line).

Remark



The second line with $r = 1$ is isomorphic to simplicial cochains.

Theorem (Arnold, Falk, Winther, 2006)

We can “mix and match” using any of the maps

$$\mathcal{P}_r \Lambda^k(\mathcal{T}) \xrightarrow{d} \mathcal{P}_{r-1} \Lambda^{k+1}(\mathcal{T}), \quad \mathcal{P}_r \Lambda^k(\mathcal{T}) \xrightarrow{d} \mathcal{P}_r^- \Lambda^{k+1}(\mathcal{T})$$

$$\mathcal{P}_r^- \Lambda^k(\mathcal{T}) \xrightarrow{d} \mathcal{P}_r^- \Lambda^{k+1}(\mathcal{T}), \quad \mathcal{P}_r^- \Lambda^k(\mathcal{T}) \xrightarrow{d} \mathcal{P}_{r-1} \Lambda^{k+1}(\mathcal{T})$$

-  Douglas N. Arnold, Richard S. Falk, and Ragnar Winther. Finite element exterior calculus, homological techniques, and applications. *Acta Numer.*, 15:1–155, 2006.
-  Douglas N. Arnold, Richard S. Falk, and Ragnar Winther. Finite element exterior calculus: from Hodge theory to numerical stability. *Bull. Amer. Math. Soc. (N.S.)*, 47(2):281–354, 2010.

How do finite element spaces yield numerical methods?

Recall our sample problem

- Given $f: \Omega \rightarrow \mathbb{R}$, find $u: \Omega \rightarrow \mathbb{R}$ vanishing on $\partial\Omega$ such that

$$\Delta u = f.$$

- Equivalently,

$$\int_{\Omega} (\Delta u)v = \int_{\Omega} fv \quad \forall v \text{ vanishing on } \partial\Omega.$$

- Integrating by parts,

$$-\int_{\Omega} \text{grad } u \cdot \text{grad } v = \int_{\Omega} fv \quad \forall v \text{ vanishing on } \partial\Omega. \quad (1)$$

Galerkin method

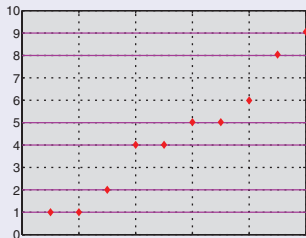
- Given f , solve (1) for u , where u and v are restricted to be in the finite element space.
- Get a finite-dimensional linear system of equations.

Bad things happen if we don't respect cohomology

Eigenvalues of the curl curl operator

On a square domain, find a vector field u (with appropriate boundary conditions) such that $\text{curl curl } u = \lambda u$.

Bad things happen if we do not respect cohomology (AFW, 2010)



- Using vector fields with full continuity yields **false** eigenvalue $\lambda = 6$.
- In contrast, using the spaces we've discussed yields the correct spectrum.

How does cohomology play a role?

- $\dim(\ker \text{curl}) = \infty$, so zero eigenspace hard to control.
- Can control if $\ker \text{curl} = \text{im grad}$ holds on the discrete level.

Good things happen if we do respect cohomology

Noether's Theorem, conservation laws, and discretization

- Noether's theorem: a system that is invariant under a transformation has a corresponding conservation law:
 - translation invariance \Rightarrow conservation of momentum
 - rotation invariance \Rightarrow conservation of angular momentum
 - time-translation invariance \Rightarrow conservation of energy
- Discretizations that respect Noether's theorem will conserve these quantities **exactly**.
 - Otherwise, the quantities will be conserved only approximately and may drift over time.

Charge conservation in electromagnetism / Yang-Mills

- curl u invariant under $u \mapsto u + \text{grad } f$
- \Rightarrow weighted average $\int \rho f$ conserved (ρ is charge).
 - continuous setting: all f allowed $\Rightarrow \rho$ conserved.
 - discrete setting: only f in finite element space (Nédélec, 1980).
- can conserve ρ even in discrete setting (—, Stern, 2021).

Further directions

Representation theory

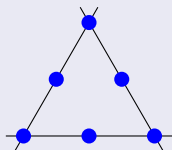
Bases for scalar fields

- Recall barycentric coordinates:

$$\{(\lambda_1, \lambda_2, \lambda_3) \in \mathbb{R}_{\geq 0}^3 \mid \lambda_1 + \lambda_2 + \lambda_3 = 1\}.$$

- Quadratic scalar fields have *monomial basis*

$$\lambda_1^2, \lambda_2^2, \lambda_3^2, \lambda_1\lambda_2, \lambda_2\lambda_3, \lambda_3\lambda_1.$$



Symmetry

- For scalar fields, the monomial basis is invariant under permuting $\lambda_1, \lambda_2, \lambda_3$.
- For vector fields, such an invariant basis may or may not exist, even up to sign.
 - In 2D and 3D, depends on the type of finite element space (e.g. $\mathcal{P}\Lambda^1, \mathcal{P}^-\Lambda^2$), and the polynomial degree modulo 3 (Licht, 2019; —, 2023).

Further directions

Riemannian geometry

So far we've discussed

- discretizing differential forms:
 - differential topology / smooth manifolds.

Riemannian geometry / Riemannian manifolds

- Must discretize the Riemannian metric:
 - Lowest order is just specifying the length of every edge of the triangulation (Regge, 1961).
 - Higher polynomial degree (Li, 2018).
- Must understand curvature:
 - Lowest order scalar curvature is just angle defect.
 - 2D: Gauss–Bonnett. General dimension: Regge, 1961.
 - Several papers towards full Riemann curvature tensor in general piecewise polynomial/smooth setting:
 - various combinations of —, Gawlik, Neunteufel, and others; 2019–2023 and in preparation.

Thank you